

# Lecture 14 QM

18.12.2020

Schrödinger equation:

$$\hat{H}\psi = i\hbar \frac{\partial \psi}{\partial t}, \quad \hat{H} = \hat{T} + \hat{V}$$

$$\hat{T} = \frac{\hat{p}^2}{2m} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} \quad \xrightarrow{3D} \quad \hat{T} = \frac{1}{2m} (\hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2)$$

$$\hat{p}_x \rightarrow -i\hbar \frac{\partial}{\partial x} \quad \hat{p}_y \rightarrow -i\hbar \frac{\partial}{\partial y} \quad \hat{p}_z \rightarrow -i\hbar \frac{\partial}{\partial z}$$

$$\hat{p} \rightarrow -i\hbar \nabla$$

$$-\frac{\hbar^2}{2m} \nabla^2 \psi + V\psi = i\hbar \frac{\partial \psi}{\partial t}$$

where  $V(\vec{r}, t)$   
 $\vec{r}(x, y, z)$

$$\nabla^2 \equiv \nabla \cdot \nabla = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \quad - \text{Laplacian}$$

$$\int d^3r |\psi(\vec{r}, t)|^2 = 1 \quad - \text{normalization}$$

$V(\vec{r}, t) = V(\vec{r})$  if the potential is time independent

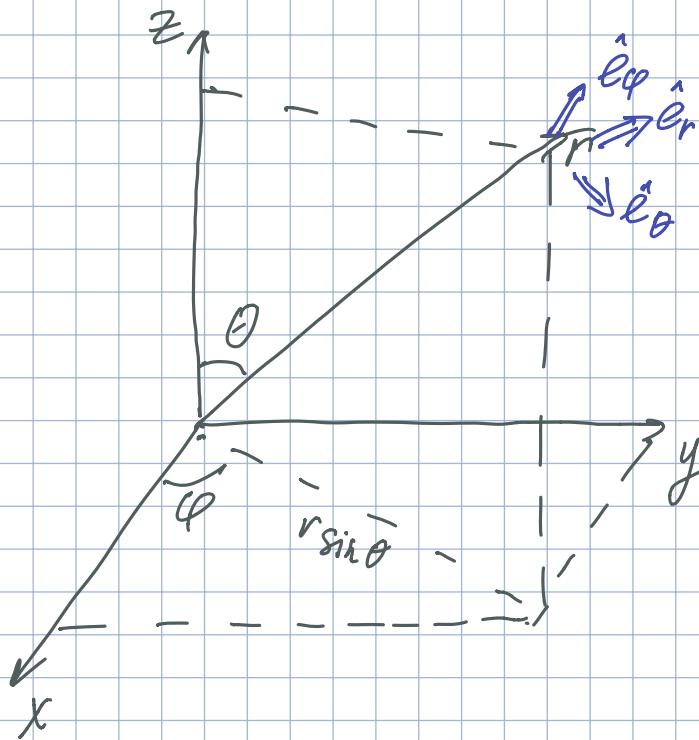
$\psi_n(\vec{r}, t) = \psi_n(\vec{r}) e^{-\frac{i}{\hbar} E_n t}$  a complete set of stationary states

$$-\frac{\hbar^2}{2m} \nabla^2 \psi_n(\vec{r}) + V\psi_n = E_n \psi_n$$

general solution:  $\bar{\psi}(\vec{r}, t) = \sum_n c_n \psi_n(\vec{r}) e^{-\frac{i}{\hbar} E_n t}$

## Central potential

$$V(\mathbf{r}) \equiv V(r), \quad r = |\mathbf{r}|$$



$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases}$$

$$\begin{cases} \hat{e}_r = \sin \theta \cos \varphi \hat{i} + \sin \theta \sin \varphi \hat{j} + \cos \theta \hat{k} \\ \hat{e}_\theta = \cos \theta \cos \varphi \hat{i} + \cos \theta \sin \varphi \hat{j} - \sin \theta \hat{k} \\ \hat{e}_\varphi = -\sin \varphi \hat{i} + \cos \varphi \hat{j} \end{cases}$$

$$\begin{aligned} \vec{\nabla} f &= \left( \frac{\partial f}{\partial x} \right) \hat{i} + \left( \frac{\partial f}{\partial y} \right) \hat{j} + \left( \frac{\partial f}{\partial z} \right) \hat{k} = \\ &= (\vec{\nabla}_r f) \hat{e}_r + (\vec{\nabla}_\theta f) \hat{e}_\theta + (\vec{\nabla}_\varphi f) \hat{e}_\varphi \end{aligned}$$

$$\begin{aligned} (\vec{\nabla}_r f) &= \hat{e}_r \vec{\nabla} f = \left( \frac{\partial f}{\partial x} \right) \frac{\sin \theta \cos \varphi}{\frac{\partial x}{\partial r}} + \left( \frac{\partial f}{\partial y} \right) \frac{\sin \theta \sin \varphi}{\frac{\partial y}{\partial r}} + \\ &+ \left( \frac{\partial f}{\partial z} \right) \frac{\cos \theta}{\frac{\partial z}{\partial r}} = \frac{\partial f}{\partial r} \end{aligned}$$

$$\begin{aligned} (\vec{\nabla}_\theta f) &= \hat{e}_\theta \vec{\nabla} f = \left( \frac{\partial f}{\partial x} \right) \frac{\cos \theta \cos \varphi}{\frac{1}{r} \frac{\partial x}{\partial \theta}} + \left( \frac{\partial f}{\partial y} \right) \frac{\cos \theta \sin \varphi}{\frac{1}{r} \frac{\partial y}{\partial \theta}} + \\ &+ \left( \frac{\partial f}{\partial z} \right) \frac{(-\sin \theta)}{\frac{1}{r} \frac{\partial z}{\partial \theta}} = \frac{1}{r} \frac{\partial f}{\partial \theta} \end{aligned}$$

$$\begin{aligned} (\vec{\nabla}_\varphi f) &= \hat{e}_\varphi \vec{\nabla} f = \left( \frac{\partial f}{\partial x} \right) \frac{(-\sin \varphi)}{\frac{1}{r \sin \theta} \frac{\partial x}{\partial \varphi}} + \left( \frac{\partial f}{\partial y} \right) \frac{\cos \varphi}{\frac{1}{r \sin \theta} \frac{\partial y}{\partial \varphi}} = \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \end{aligned}$$

$$\nabla = \hat{e}_r \frac{\partial}{\partial r} + \hat{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{e}_\varphi \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi}$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$

Time-independent Schrödinger equation

$$-\frac{\hbar^2}{2m} \left[ \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \psi}{\partial \varphi^2} \right] + V(r)\psi = E\psi$$

$$\psi(r, \theta, \varphi) = R(r) Y(\theta, \varphi)$$

$$-\frac{\hbar^2}{2m} \left[ \frac{Y}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{R}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{R}{r^2 \sin^2 \theta} \frac{\partial^2 Y}{\partial \varphi^2} \right] + V(r)RY = ERY \quad \left| \begin{array}{l} \text{R} \\ \text{Y} \end{array} \right. \left( \frac{-2m\hbar^2}{\hbar} \right)$$

$$\left\{ \frac{1}{R} \frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) - \frac{2m r^2}{\hbar^2} [V(r) - E] \right\} +$$

$$\underbrace{\frac{1}{Y} \left\{ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \varphi^2} \right\}}_{\substack{\theta, \varphi \\ l(l+1) - \text{constant}}} = 0$$

depends only on r

$$\frac{1}{R} \frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) - \frac{2m r^2}{\hbar^2} [V(r) - E] = l(l+1) \quad \text{radial equation}$$

$$\frac{1}{Y} \left\{ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \varphi^2} \right\} = -l(l+1) \quad \text{angular equation}$$

## Angular equation

$$\sin\theta \frac{\partial}{\partial\theta} \left( \sin\theta \frac{\partial Y}{\partial\theta} \right) + \frac{\partial^2 Y}{\partial\varphi^2} = -l(l+1) \sin^2\theta Y$$

$$Y(\theta, \varphi) = \Theta(\theta) \Phi(\varphi)$$

$$\underbrace{\left\{ \frac{1}{\Theta} \sin\theta \frac{\partial}{\partial\theta} \left( \sin\theta \frac{\partial\Theta}{\partial\theta} \right) + l(l+1) \sin^2\theta \right\}}_{\text{depends only on } \theta} + \underbrace{\frac{1}{\Phi} \frac{\partial^2\Phi}{\partial\varphi^2}}_{\varphi} = 0$$

$$\frac{1}{\Theta} \sin\theta \frac{d}{d\theta} \left( \sin\theta \frac{d\Theta}{d\theta} \right) + l(l+1) \sin^2\theta = m^2$$

$$\frac{1}{\Phi} \frac{\partial^2\Phi}{\partial\varphi^2} = -m^2$$

$$\Phi(\varphi) = e^{im\varphi}$$

$$\Phi(\varphi + 2\pi) = \Phi(\varphi) \quad e^{im2\pi} = 1$$

$$\Rightarrow m = 0, \pm 1, \pm 2, \dots \text{ integer}$$

$$\sin\theta \frac{d}{d\theta} \left[ \sin\theta \frac{d\Theta}{d\theta} \right] + [l(l+1) \sin^2\theta - m^2] \Theta = 0$$

$$x = \cos\theta \quad \frac{d}{d\theta} = -\sin\theta \frac{d}{dx}$$

$$-\sin^2\theta \frac{d}{dx} \left[ -\sin^2\theta \frac{d\Theta}{dx} \right] + [l(l+1) \sin^2\theta - m^2] \Theta = 0$$

$$\sin^2\theta = 1 - x^2$$

$$(1-x^2) \frac{d}{dx} \left[ (1-x^2) \frac{d\Theta}{dx} \right] + [l(l+1)(1-x^2) - m^2] \Theta = 0$$

$$(1-x^2)^2 \frac{d^2\Theta}{dx^2} - 2x(1-x^2) \frac{d\Theta}{dx} + [l(l+1)(1-x^2) - m^2] \Theta = 0$$

$$| : (1-x^2)$$

$$(1-x^2) \frac{d^2 \Theta}{dx^2} - 2x \frac{d\Theta}{dx} + \left[ l(l+1) - \frac{m^2}{1-x^2} \right] \Theta = 0$$

$$\Theta(\theta) = A P_l^m(\cos \theta)$$

↳ associated Legendre functions

$$P_l^m(x) \equiv (1-x^2)^{m/2} \frac{d^m}{dx^m} P_l(x)$$

↳ Legendre polynomials

$$P_l^0(x) = P_l(x)$$

Rodrigues formula

$$P_l(x) \equiv \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2-1)^l \quad l - \text{positive integer}$$

Special cases:

$$P_0(x) = 1$$

$$P_1(x) = \frac{1}{2} \frac{d}{dx} (x^2-1) = x$$

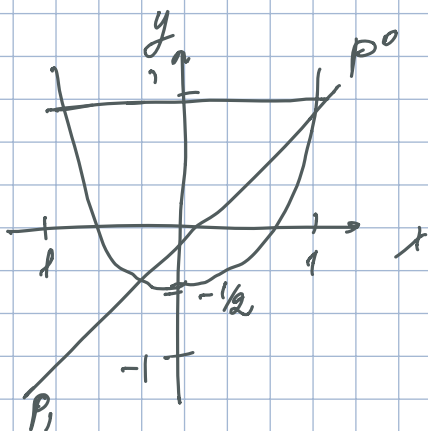
$$P_2(x) = \frac{1}{4 \cdot 2} \frac{d^2}{dx^2} (x^2-1)^2 = \frac{1}{2} \frac{d}{dx} [(x^2-1)x] = \frac{1}{2} (3x^2-1)$$

⋮

$P_l(x)$  - polynomial of degree  $l$  in  $x$

$l$  even  $\rightarrow P_l$  is even in  $x$

$l$  odd  $\rightarrow P_l$  is odd in  $x$



$P_l^m$  special cases:

$l \Rightarrow (2l+1)$  possible values of  $m$

$$m = -l, -l+1, \dots, 0, 1, \dots, l-1, l$$

$$P_0^0 = 1$$

$$P_l^m = (\sqrt{1-x^2})^m \frac{d^m}{dx^m} P_l(x) = (\sqrt{1-x^2}) \frac{d^m}{dx^m} x$$

$$P_1^0 = 0$$

$$P_1^1 = \sqrt{1-x^2}$$

$$P_2^0 = P_2 = \frac{1}{2} (3x^2 - 1)$$

$$m \neq 0 \quad P_2^m = (1-x^2)^{m/2} \frac{d^m}{dx^m} \frac{1}{2} (3x^2 - 1)$$

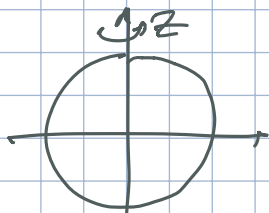
$$P_2^1(x) = \sqrt{1-x^2} 3x$$

$$P_2^2(x) = 3(1-x^2)$$

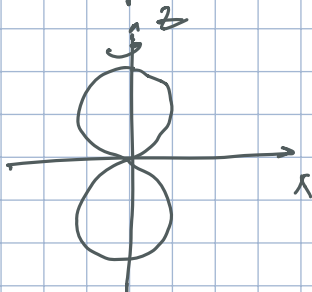
$m$  odd  $\rightarrow P_l^m$  is polynomial  $\times \sqrt{1-x^2}$

$m$  even  $\rightarrow P_l^m$  is polynomial

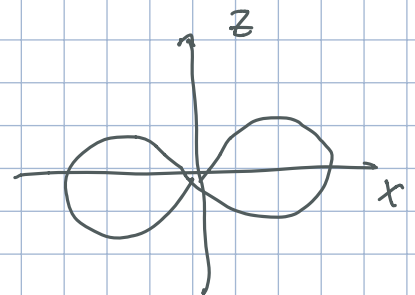
$$P_0^0 = 1$$



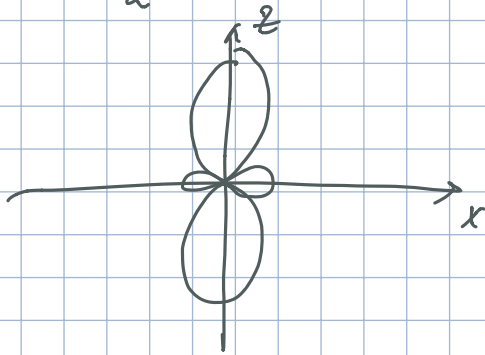
$$P_1^0 = \cos \theta$$



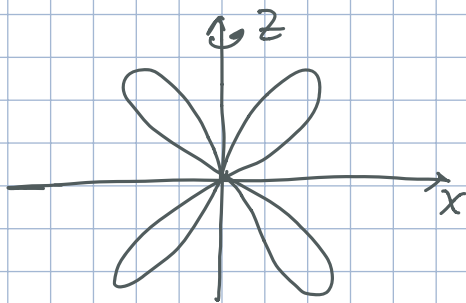
$$P_1^1 = \sin \theta$$



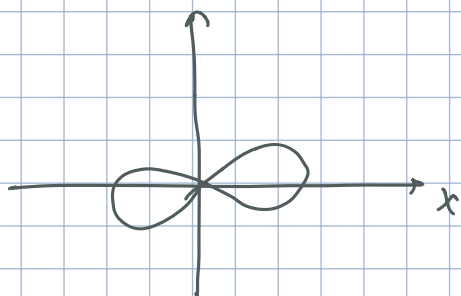
$$P_2^{00} = \frac{1}{2} (3 \cos^2 \theta - 1)$$



$$P_2^{10} = 3 \sin \theta \cos \theta$$



$$P_2^{20} = 3 \sin^2 \theta$$



$$\int d^3 \vec{r} |\psi|^2 = 1$$

$$d^3 \vec{r} = r^2 \sin \theta dr d\theta d\varphi$$

$$\psi(\vec{r}) = R(r) Y(\theta, \varphi)$$

$$\int dr r^2 |R(r)|^2 \int d\varphi d\theta \sin \theta |Y(\theta, \varphi)|^2 = 1$$

$$\int_0^\infty dr r^2 |R(r)|^2 = 1$$

normalization

$$\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin \theta |Y(\theta, \varphi)|^2 = 1$$

$$Y(\theta, \varphi) = Y_{l,m}(\theta, \varphi) = (-1)^m \frac{\sqrt{(2l+1)(l-m)!}}{4\pi(l+m)!} e^{im\varphi} P_l^m(\cos \theta)$$

spherical harmonics

$$Y_{l,-m}(\theta, \varphi) = (-1)^m Y_{l,m}^*(\theta, \varphi)$$

## Radial equation

$$\frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) - \frac{2mr^2}{\hbar^2} [V(r) - E] R = l(l+1) R$$

$$U(r) \equiv r R(r)$$

$$R = \frac{U}{r}$$

$$\frac{dR}{dr} = \frac{1}{r^2} \left( r \frac{dU}{dr} - U \right)$$

$$\frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) = \frac{dU}{dr} + r^2 \frac{d^2 U}{dr^2} - \frac{dU}{dr}$$

$$\left\| -\frac{\hbar^2}{2m} \frac{d^2 U}{dr^2} + \underbrace{\left[ V + \frac{\hbar^2}{2m} \frac{l(l+1)}{r^2} \right]}_{V_{\text{eff}} - \text{effective potential}} U = E U$$

$$\frac{\hbar^2}{2m} \frac{l(l+1)}{r^2} - \text{repulsive centrifugal potential}$$

$$\text{normalization} \quad \int_0^{\infty} dr |U(r)|^2 = 1$$